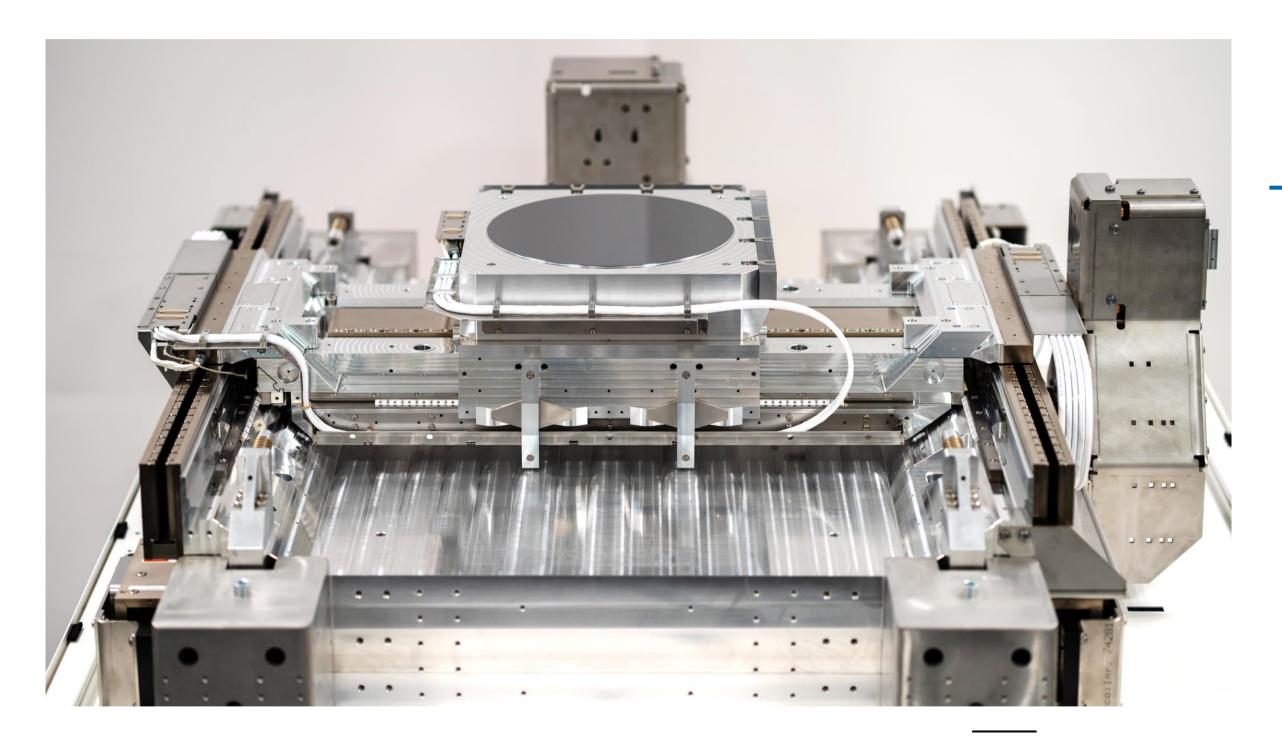


# TABLE OF CONTENTS



A Pass	sion for Technology	3
Overv	iew	4
Iris Lir	ne	(
Feat	tures	-
M/L	Performance Specifications	}
M	Mechanical Specifications	(
L	Mechanical Specifications	1(
Defini	tions	1′
Conta	ct	12



Linear motors integrated in a motion stage

### A PASSION FOR TECHNOLOGY



#### Knowledge

Engineering excellence is the driving force behind linear motor innovation in both design and manufacturing. Prodrive has a highly skilled group of (electro-)mechanical engineers capable of customizing linear motor technology towards your needs.

#### Quality

Quality is in the DNA of Prodrive Technologies. With a long history in electronics manufacturing, Prodrive continues in the area of linear motor manufacturing with the same philosophy and processes, setting a new standard within the linear motor market.

#### Automation

Design for manufacturing is key to reduce cost and guarantee quality. Winding, assembly, vacuum potting and magnet gluing are highly automated processes which guarantees a constant quality at minimum cost.

#### Time to market

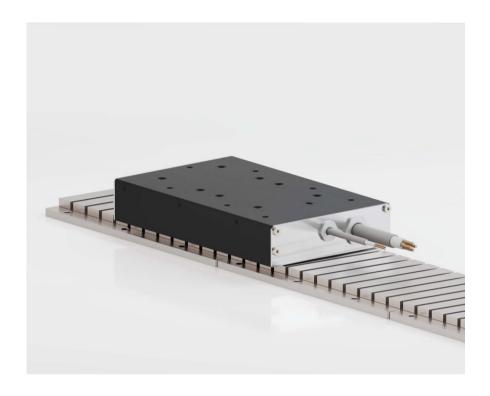
Due to the agility of Prodrive Technologies' large development department, customization can be performed in a very short time, providing a short time to market for challenging mechatronic applications.



Prodrive Technologies HQ Campus, The Netherlands

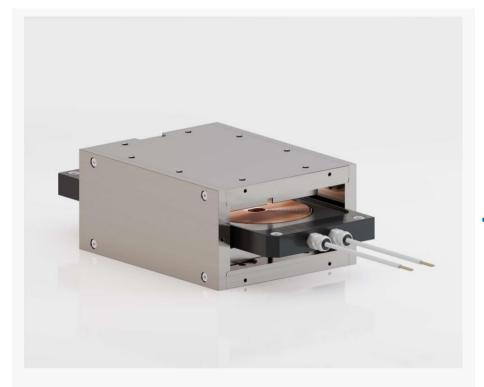
### **OVERVIEW**











#### Chiron

The Chiron line offers iron core linear motors which are optimized for high force and high efficiency. Find the optimal fit for your application due to the many different available form factors.

#### Phoenix

The Phoenix line offers ironless linear motors, for applications requiring an extremely low force ripple for excellent servo performance without attraction forces. Available in a large range of sizes.

#### Gryphon

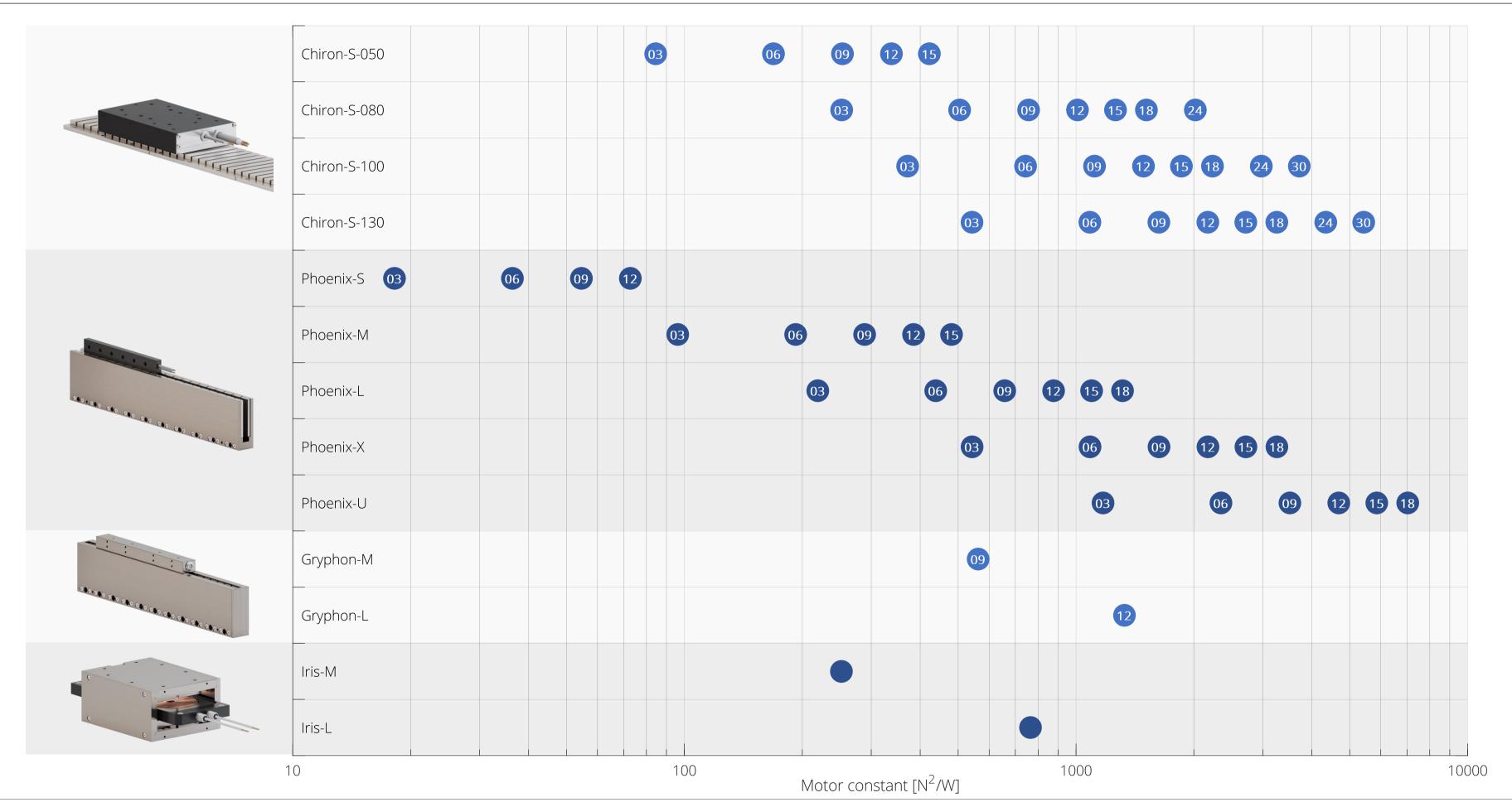
The Gryphon line offers a cost-effective solution for vacuum-compatible ironless linear motors. These motors also contain features providing magnetic shielding.

#### Iris

For short stroke applications requiring a relatively large displacement in three directions, the Iris line provides a high force density with zero attraction forces in a rectangular form factor.

# OVERVIEW







The Iris line offers short stroke linear motors with a rectangular form factor. These motors also contain features providing magnetic shielding.



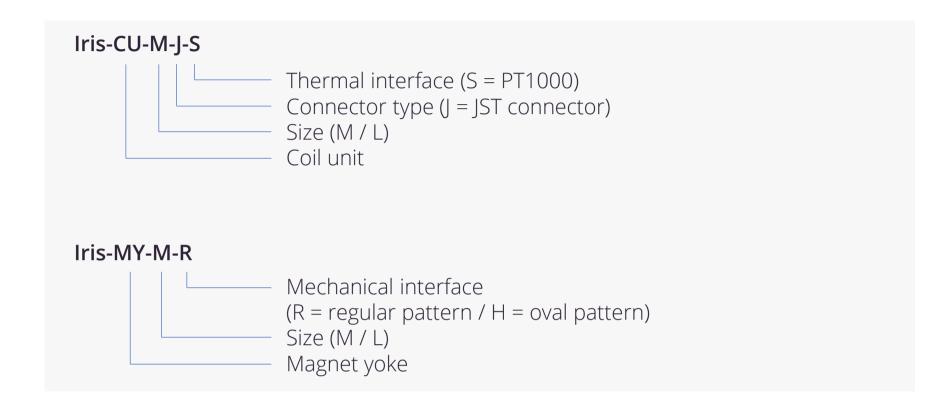
Iris line in medium and large configuration

# IRIS LINE - FEATURES





Iris in exploded view



- Different sizes for optimal mechanical integration
- Magnets are shorter than the back iron which improves magnetic shielding
- Mounting interface for additional cover plates
- Coil units have a temperature sensor (PT1000)
- Coil unit housing optimized for heat transfer and force bandwidth

# IRIS-M/L PERFORMANCE SPECIFICATIONS



	Parameter	Symbol	Unit	T <sub>coil</sub> (°C)	CU-M	CU-L
<u>۔</u>	Peak force ( $\alpha_T$ = 5°C/s increase)	Fp	Ν	20	458	1178
Jec	Continuous force	$F_c$	Ν	100	82	173
гоп	Attraction force ( $I = 0$ )	F <sub>att</sub>	N	-	0	0
Electromech.	Motor constant	S	$N^2/W$	20	252	765
画	Force constant	K <sub>f</sub>	N/A	-	19	48
	Maximum dc bus voltage	$V_{dc}$	V	-	100	100
<del>-</del>	Phase resistance	R <sub>ph,20</sub>	Ohm	20	1.5	3.0
iric	Phase inductance	L <sub>ph</sub>	mΗ	-	3.4	13.2
Electrical	EMF constant	K <sub>e</sub>	Vs/m	-	19	48
ш	Maximum rms current	Ip	Α	20	24.0	24.6
	Continuous rms current	l <sub>c</sub>	Α	100	4.3	3.6
_	Continuous dissipation	$P_{d,c}$	W	100	35	52
ma	Thermal resistance	$R_{th}$	K/W	-	2.30	1.55
Therma	Coil unit heat capacity	C <sub>th</sub>	J/K	-	167	363
	Thermal time constant	τ <sub>th</sub>	S	-	384	563

#### Notes

- Specifications are based upon a magnet temperature of 20°C
- Thermal resistance is measured with a convection of 10W/m<sup>2</sup>K

#### Product marking / approvals



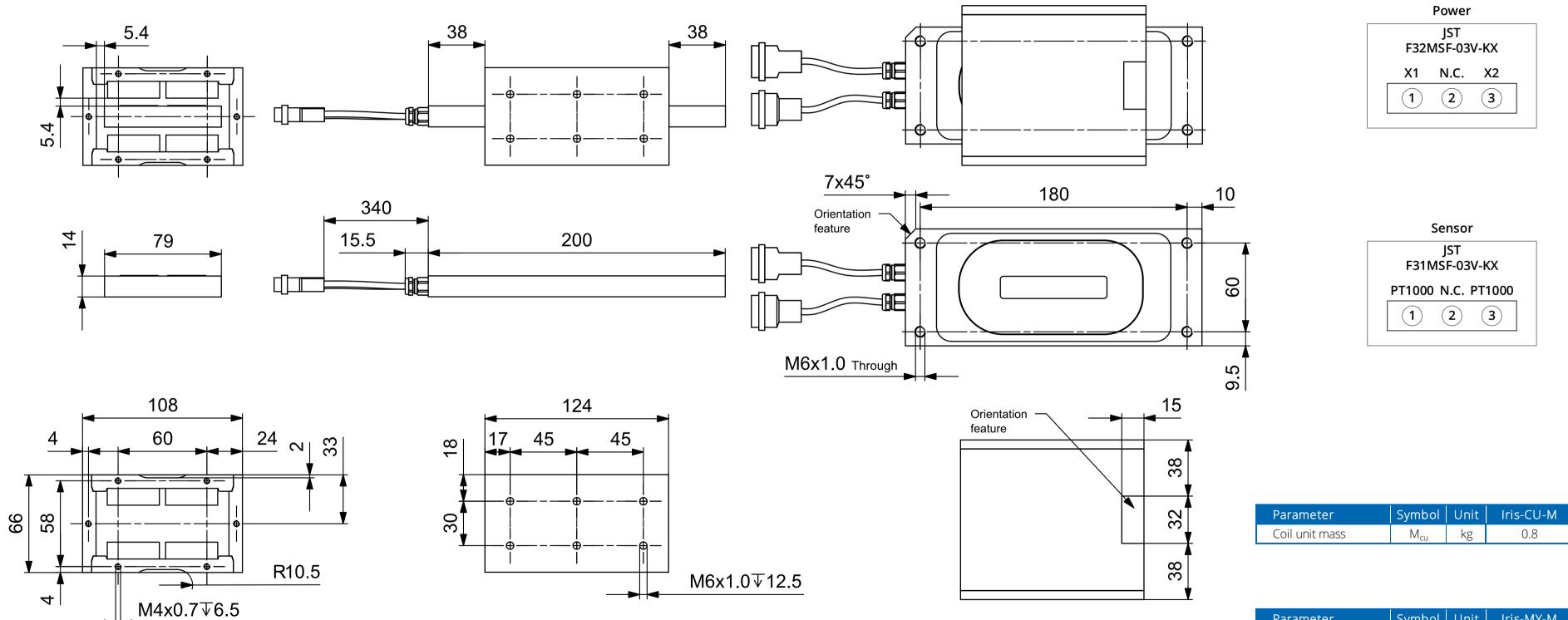


## IRIS-M MECHANICAL SPECIFICATIONS



Coil unit: Iris-CU-M-J-S Magnet yoke: Iris-MY-M-R

Drawings of remaining models on request



Parameter	Symbol	Unit	Iris-CU-M
Coil unit mass	$M_{cu}$	kg	0.8

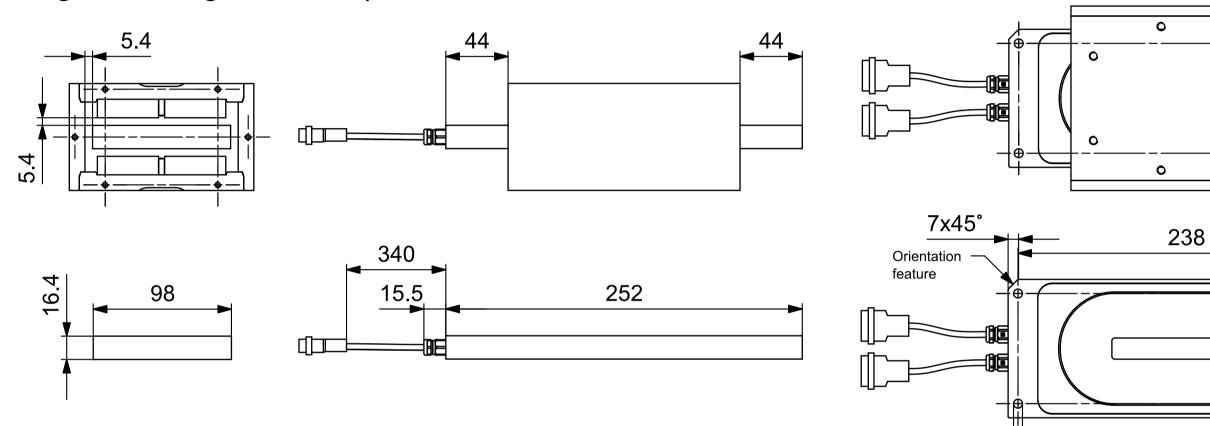
Parameter	Symbol	Unit	Iris-MY-M
Magnet yoke mass	$M_{my}$	kg	3.8

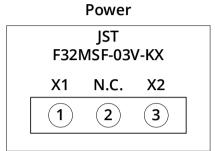
## IRIS-L MECHANICAL SPECIFICATIONS

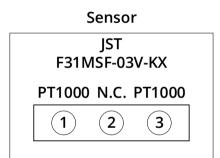


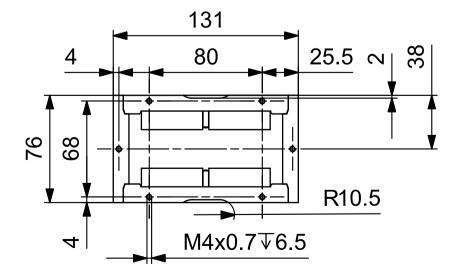
Coil unit: Iris-CU-L-J-S Magnet yoke: Iris-MY-L-H

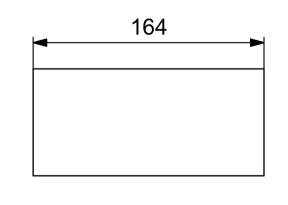
Drawings of remaining models on request



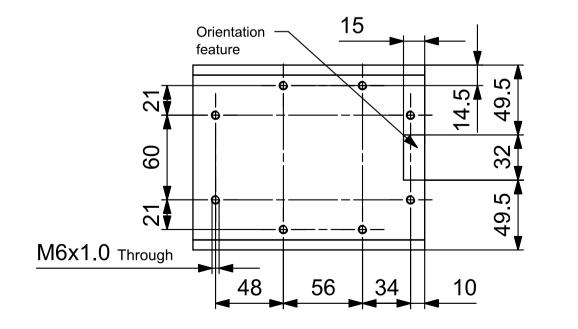








M6x1.0 Through



Parameter	Symbol	Unit	lris-CU-L
Coil unit mass	$M_{cu}$	kg	1.5

Parameter	Symbol	Unit	Iris-MY-L
Magnet yoke mass	$M_{my}$	kg	7.6

# DEFINITIONS



Description	Equation	Unit	Remarks
Phase resistance at T <sub>coil</sub>	$R_{ph} = R_{ph,20} (1+0.0039(T_{coil}-20))$	Ohm	
Force constant at no load	$K_f = K_e$	N/A	
Continuous dissipation	$P_{d,c} = (T_{coil} - T_{amb})/R_{th}$	W	Only copper losses are considered. This catalogue considers T <sub>amb</sub> = 20°C.
Peak dissipation	$P_{d,p} = C_{th} \alpha_T$	W	$\alpha_{\text{T}}$ is mentioned at the peak force specification.
Continuous rms current	$I_{c} = \min\left(\sqrt{\frac{P_{d,c}}{R_{ph}}}, \frac{V_{dc}}{R_{ph}}\right)$	A	Limited either by continuous dissipation or dc voltage and resistance or cable/connector ratings (if applicable).
Peak rms current	$I_{p} = \min\left(\sqrt{\frac{P_{d,p}}{R_{ph,20}}}, \frac{V_{dc}}{R_{ph,20}}\right)$	А	Limited either by peak dissipation or dc voltage and resistance or cable/connector ratings (if applicable).
Thermal time constant	$\tau_{th} = C_{th}R_{th}$	S	
Continuous force	$F_c = K_f I_c$	N	
Peak force	$F_p = K_f I_p$	N	
Motor constant	$S = \frac{K_f^2}{R_{ph,20}}$	N <sup>2</sup> /W	
Maximum velocity (F = 0)	$v_{\rm m} = \frac{V_{\rm dc}}{K_{\rm e}}$	m/s	Iron losses are not considered.



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